

#### www.motorcontrolwarehouse.co.uk

| Document number | MCW - E2 - 003   |  |
|-----------------|--|--|
| Revision        | 0.0  |  |
| Author          | Gareth Lloyd   |  |
| Product         | Optidrive E2 IP20 & IP66 non-switched.                           |  |
|                 | Optidrive IP66 switched can be configured if the on-board switch |  |
|                 | connections are removed.   |  |

| Title E2 Parameter P-15 = 1 Set-up Guide |
|--|
|--|

| Summary | This document gives set-up information on the Optidrive E2 |
|---------|--|
|         | parameter P-15 = 1   |

#### NOTE: Please read in conjunction with the Optidrive E2 User Guide.

This set-up guide gives information on the easiest way to set up the E2 for basic motor control. This set up is from default settings - as the drive comes out of the box from the factory. This assumes a standard 50Hz AC induction motor.

This set up uses 3 switches and a potentiometer to:

Enable the drive, select between the preset speeds or potentiometer speed reference, select between 2 preset speeds and control motor speed.

## **Parameter settings**

In most cases, the default maximum and minimum frequencies and motor rated voltage do not need adjusting because the default settings are OK for the majority of applications and motors.

The acceleration and deceleration times may need some adjustment depending on the application and load type.

The motor rated current (P-08) must be set to the motor nameplate current to provide motor protection in case of motor overload.

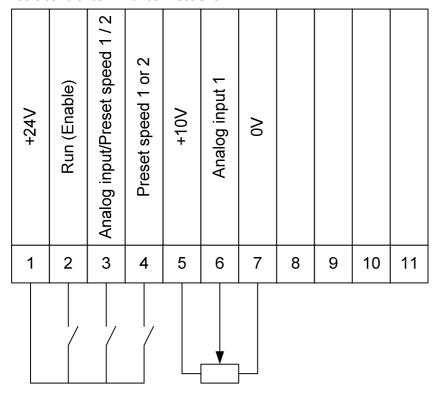
In the majority of applications, the motor rated speed (P-10) does not need setting.

| Parameter | Description            | Default setting | Description                        |  |
|-----------|------------------------|-----------------|------------------------------------|--|
| P-01      | Maximum frequency      | 50Hz            | Maximum frequency/speed the motor  |  |
|           |                        |                 | will run at:                       |  |
|           |                        |                 | 2 pole motor: 3000rpm              |  |
|           |                        |                 | 4 pole motor: 1500rpm              |  |
|           |                        |                 | 6 pole motor: 1000rpm              |  |
|           |                        |                 | 8 pole motor 750rpm                |  |
| P-02      | Minimum frequency      | 0Hz             | Minimum frequency/speed the motor  |  |
|           |                        |                 | will run at (0 rpm)                |  |
| P-03      | Acceleration time      | 5 seconds       | Acceleration time from 0Hz to 50Hz |  |
| P-04      | Deceleration time      | 5 seconds       | Deceleration time from 50Hz to 0Hz |  |
| P-07      | Motor rated voltage    | 230V/400V       | Set to the motor nameplate voltage |  |
| P-08      | Motor rated current    | Drive dependant | Set to the motor nameplate current |  |
| P-14      | Extended parameter     | 0               | Set to 101 to allow extended       |  |
|           | access                 |                 | parameter access                   |  |
| P-15      | Digital input function | 0               | Set to 1                           |  |
|           | select                 |                 |                                    |  |
| P-20      | Preset speed 1         | 0.0Hz           | Set to the desired frequency/speed |  |
| P-21      | Preset speed 2         | 0.0Hz           | Set to the desired frequency/speed |  |

**NOTE:** Please check that the motor terminal box connections are correct for the voltage you are applying to the motor:

| Incoming Supply Voltage | Motor Nameplate Voltages | Connections |
|-------------------------|--------------------------|-------------|
| 230V                    | 230V / 400V              | Delta       |
| 400V                    | 400V / 690V              | △ U V W     |
| 400V                    | 230V / 400V              | Star        |

#### **Basic control terminal connections**



#### **Terminal 1**

+24VDC User supply

## Terminal 2: Run (Enable)

Switch Open: Drive stopped

Switch Closed: Drive running / enabled

## Terminal 3: Analog reference or Preset speed 1 / 2

Switch Open: Analog speed reference (potentiometer)

Switch Closed: Speed is either preset speed 1 or 2 depending on terminal 4

#### Terminal 4: Preset speed 1 or 2

Switch Open: Preset speed 1. Speed is set in parameter P-20 Switch Closed: Preset speed 2. Speed is set in parameter P-21

#### Terminal 5: +10V

Speed potentiometer +10V reference

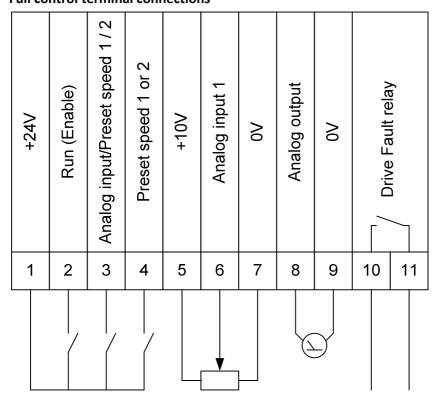
## **Terminal 6: Analog input**

Speed potentiometer wiper: 0 to +10V

## Terminal 7: 0V

Speed potentiometer 0V reference

### **Full control terminal connections**



#### **Terminal 1**

+24VDC User supply

## Terminal 2: Run (Enable)

Switch Open: Drive stopped

Switch Closed: Drive running / enabled

# Terminal 3: Analog reference or Constant speed 1/2

Switch Open: Analog speed reference (potentiometer)

Switch Closed: Speed is either preset speed 1 or 2 depending on terminal 4

#### Terminal 4: Constant speed 1 or 2

Switch Open: Preset speed 1. Speed is set in parameter P-20 Switch Closed: Preset speed 2. Speed is set in parameter P-21

# Terminal 5: +10V

Speed potentiometer +10V reference

## **Terminal 6: Analog input**

Speed potentiometer wiper: 0 to +10V

## Terminal 7: 0V

Speed potentiometer 0V reference

# Terminal 8: Analog output - speed

0 to  $\pm$ 10VDC output proportional to motor speed (0 to  $\pm$ 50Hz = 0 to  $\pm$ 10V)

Terminals 10 & 11: Drive Healthy relay

Relay Open: Drive fault Relay closed: Drive healthy